



Serial Communication

This course is for participants who will use a MELSEC-Q series serial communication module for the first time.

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Introduction Purpose of the Course

This course explains the basics of a serial communication module that is compatible with the MELSEC-Q series programmable controller, and is designed for those who will use the module for the first time.

By taking this course, a participant will understand the data communication mechanism, specifications, settings and the start-up method of the serial communication module.

This course requires the basic knowledge of MELSEC-Q series programmable controllers, sequence programs, and GX Works2.

Taking the following courses is recommended before starting this course.

- 1. MELSEC-Q Series Basics Course
- 2. GX Works2 Basics Course
- 3. Intelligent Function Module Course

Introduction Course Structure



The contents of this course are as follows. We recommend that you start from Chapter 1.

Chapter 1 - Serial Communication Basics

Explains the serial communication basics.

Chapter 2 - Serial Communication Module Details

Explains the serial communication module types, component names and functions of a module, and connection methods.

Chapter 3 - Initial Configuration

Explains how to setup a serial communication module and how to program it using dedicated instructions.

Chapter 4 - Troubleshooting

Explains the network diagnostic procedure for troubleshooting.

Final Test

Passing grade: 60% and higher



Introduction How to Use This e-Learning Tool



| Go to the next page | | Go to the next page. |
|---------------------------|------------|---|
| Back to the previous page | (1) | Back to the previous page. |
| Move to the desired page | TOC | "Table of Contents" will be displayed, enabling you to navigate to the desired page. |
| Exit the learning | X | Exit the learning. Window such as "Contents" screen and the learning will be closed. |

Introduction Cautions for Use



Safety precautions

When you learn by using actual products, please carefully read the safety precautions in the corresponding manuals.

Precautions in this course

- The displayed screens of the software version that you use may differ from those in this course.

This course uses the following software version:

- GX Works2 Version 1.493P

Chapter 1 Serial Communication Basics



Chapter 1 describes the serial communication module basics.

In Chapter 1, you will understand how a serial communication module is used, its main functions, and its data communication method.

- 1.1 Communication Parameters
- 1.2 Communication Protocols
- 1.3 Flow Control
- 1.4 Interface Types
- 1.5 Data Division
- 1.6 Summary

Basic knowledge of serial communication

Serial communication is a mature technology that has been used for many years. It is still popular today as a data communication method for devices such as a measuring instrument and bar code reader. One reason of the popularity is their inexpensive parts.

This course features RS-232, a representative interface for serial communication.

In serial communication with a serial communication module, various device types can be connected comparatively freely. However, the communication specifications of the connected device (3rd party device) must be fully understood to establish normal communication.

Communication specifications are roughly classified into the following:

- Communication parameters
- · Communication protocol
- Flow control

Both of the communicating devices must satisfy the communication specifications at the design stage.

Communication Parameters



Below are communication parameters that are important to serial communication:

Number of data bits

An alphanumeric character is expressed in 7 bits. Therefore, when sending only a numeric or alphabetical character, data size can be reduced by selecting 7 bits.

Parity bit

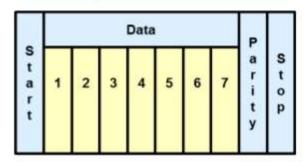
This needs to be set to detect data corruption caused by noise, etc.

Stop bit

This bit indicates the end of data.

Bit rate

The bit rate is the number of bits sent per second. This is also called the transmission speed. A higher bit rate means a shorter transmission time. Adjust the bit rate when the communication is affected by noise, etc.



All of the above parameters must be set the same at both of the communicating devices.

The parameters of many devices are non-changeable. Therefore, check the specifications of the 3rd party device and adjust the serial communication modules communication parameters.



1.2 **Communication Protocols**

A communication protocol is a set of conventions adopted by the devices connected to a network.

Examples of communication protocols (rules) include:

- When data has been received normally, a specific code is returned to report a normal reception.
- When an error has occurred, an error code is sent to report the error occurrence.

Since these communication protocols are determined by the connected 3rd party device, the specifications of the device must be checked.

To set a communication protocol for a serial communication module, the user can use the "predefined protocol support function" of GX Works2 (details are given in later chapters), and simply select the communication protocol from the existing protocol options.

New protocols can also be added if the desired protocol is not found. Doing so allows data to be sent or received automatically via compatible 3rd party devices, without using sequence programs.

Flow Control





Flow control is a procedure that ensures the data receiving side receives all the transmitted data. Flow control is roughly classified into two types: hardware flow control and software flow control.

Hardware flow control

Adjusts data send timing by using a flow control line, which is installed separately from the signal line, in the same cable. Using the flow control line, data receive information is returned to the source.

The serial communication module uses DTR/DSR hardware flow control. Connection with an RTS/CTS control device is possible but such connections must be carefully designed.

Software flow control

Adjusts data send timing by using specific codes. When using this method, data receive information is returned to the source.

The Xon/Xoff control, which is a representative software flow control type, is the same as the DC1/DC3 control, which is an option selectable at GX Works2.

Some devices do not support flow control. In such cases, the serial communication module should perform operations such as:

- · Adjust the send interval.
- Detect when the receiving side fails to receive data, and if that happens, discard the unreceived data.



Interface Types



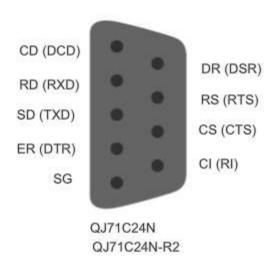
RS-232

The RS-232 interface is often connected via a D-sub connector. A function is assigned to each contact pin according to the RS-232 standard.

Note that the RS-232 compatible serial port of a personal computer, etc. is a male port with protruding pins, but the RS-232 port of a programmable controller is a female port.

A signal cable consists of a communication line and a control line. Which of the two lines is used depends on the communication specifications of the 3rd party device.

If the desired wiring is not commercially available, the connector must be configured to accept such wiring.



| Pin number | Signal code | Signal function | Signal direction Module <=> 3rd party device |
|---------------|-------------|---|---|
| 1 | CD (DCD) | Detection of data channel- receiving carrier | — |
| 2 | RD (RXD) | Received data | ← |
| 3 | SD (TXD) | Sent data | |
| 4 | ER (DTR) | Data terminal ready | |
| 5 | SG | Signal ground | ←⇒ |
| 6 | DR (DSR) | Data set ready | ← |
| 7 | RS (RTS) | Request to send | |
| 8 | CS (CTS) | Clear to send | ← |
| 9 | CI (RI) | Ring indicator | |



1.4 Interface Types



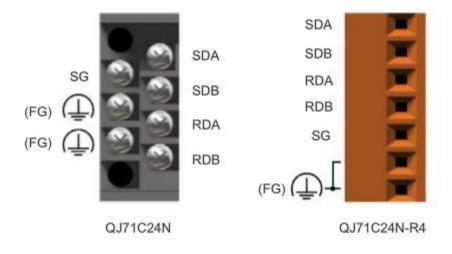
RS-422 and RS-485

When these interfaces are used, devices communicate by differential signals. For differential signals, a pair of signal lines is used for one signal.

Differential signals are comparatively resistant to noise and suitable for long-distance transmission.

As no control line is used, software flow control is used when flow control is required.

The RS-422 interface uses one signal line for sending data and another for receiving. The RS-485 interface uses one signal line for both transmission and reception.



| Signal code | Signal name | Signal direction Module <=>3rd party device |
|-------------|-------------------|---|
| SDA | Sent data (+) | |
| SDB | Sent data (-) | |
| RDA | Received data (+) | — |
| RDB | Received data (-) | — |
| SG | Signal ground | ← |
| FG | Frame ground | ← |
| FG | Frame ground | ← |

This course explains the highly versatile RS-232 interface.

1.5 **Data Division**

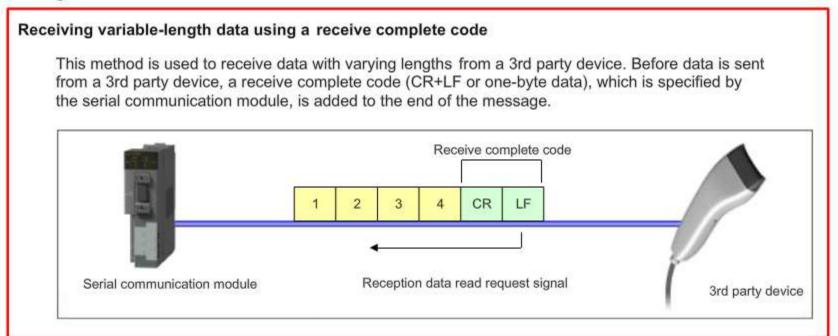




When data is received, it is usually divided into parts of a certain length.

There are two data division methods: division by the number of data and division by a receive complete code. Each method depends on the communication specifications of the 3rd party device, therefore make sure to confirm the specifications.

If necessary, a receive complete code and the received data count can be changed from their default settings.



The example system in this course receives data using a receive complete code.

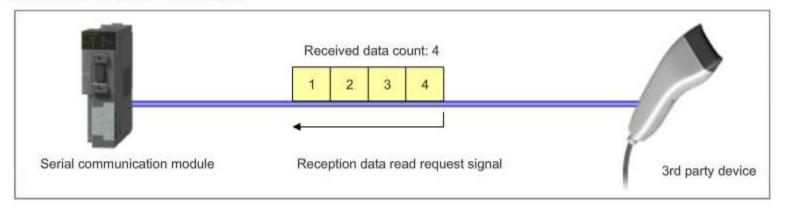
1.5 Data Division



Receiving fixed-length data using the received data count

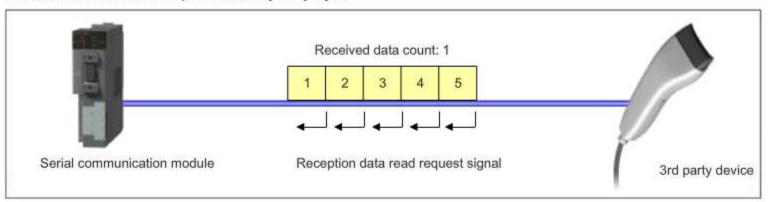
This method is used to receive data with a fixed length. Since the data length is fixed by the 3rd party device, a receive complete code is unnecessary.

The 3rd party device sends the data amount that is specified by the received data count setting of the serial communication module.



Advanced technique: receiving variable-length data with no receive complete code

If a receive complete code is not added to the data with varying lengths sent from the 3rd party device, the data is received and processed byte by byte.



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1.6 Summary

In this chapter, you have learned:

- · Communication parameters
- · Communication protocols
- · Flow control

- · Interface types
- · Data division

Important points

| Communication parameters | Important parameters in serial communication are the number of data bits, parity bit, stop bit, and bit rate. |
|----------------------------------|---|
| Fixed length and variable length | Communication protocols handle two types of data; fixed-length data and variable-length data. |
| Flow control | Flow control is roughly classified into two types: hardware flow control and software flow control |
| Interface type | Interfaces of a serial communication module are RS-232, RS-422, and RS-485. |
| Data division | The received data is divided by the receive data count or a receive complete code. |





Chapter 2 Serial Communication Module Details

Chapter 2 describes the serial communication module types, component names and functionality of a module, and the connection methods.

- 2.1 Serial Communication Module Types
- 2.2 Communication Cable Connection
- 2.3 Serial Communication Module Communication Protocols
- 2.4 Serial Communication Module Configuration
- 2.5 Summary

Serial Communication Module Types



This section describes the serial communication module types, the component names of a module, and its LED indicators.

Serial communication module

A serial communication module is an intelligent function module. A serial communication module connects an external device such as a measuring instrument and bar code reader, to a Q-series CPU module through its RS-232 or RS-422/485 interface, which are typical serial communication interfaces, to enable data communication between the connected devices.

Each module provides two communication channels that can be simultaneously used.

Three module types, with different combinations of interfaces, are available.

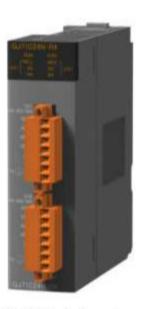






RS-232: 2 channels

QJ71C24N-R4



RS-422/485: 2 channels

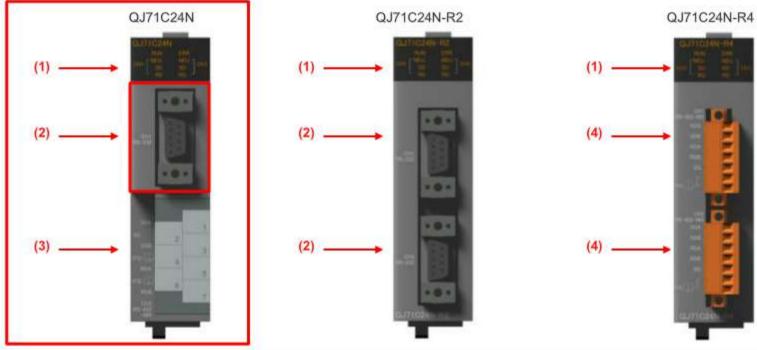
This course uses the QJ71C24N single channel RS-232 interface as an example.

2.1.1 Serial communication module components

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This section describes the serial communication module components and their functionality.

Component names and functionality



| No. Name Fi | | Function |
|---|----------------------|--|
| (1) LED indicators Please refer to the list of LED indicators on the next page. | | Please refer to the list of LED indicators on the next page. |
| (2) RS-232 interface For serial communication with a 3rd party device (D-sub, 9-pin, female connection) | | For serial communication with a 3rd party device (D-sub, 9-pin, female connector) |
| (3) RS-422/485 interface For serial communication with a 3rd party device (2-piece terminal block*) | | For serial communication with a 3rd party device (2-piece terminal block*) |
| (4) | RS-422/485 interface | For serial communication with a 3rd party device (2-piece plug-in connector socket block*) |

^{*} The 2-piece terminal block and the 2-piece plug-in connector socket block can be removed by loosening their screws.

Each terminal block can be replaced on the module easily without removing the wires in the case of a module breakdown.



2.1.2 LED indicators and their functions



This section describes the functionality of the LED indicators that are on a serial communication module.

LED indicators



| LED | | | | | Corresponding protocol | | | |
|--------|--|-----------------------------|----------------------------------|-------------------------|------------------------|---------------|---------------|---------------|
| СН | indicator Function On or flashing Off name | мс | Non procedure | Bi- directional | Predefined | | | |
| | RUN | Indicates normal operation | Normal | Abnormal, reset | - Valid | 17 | Valid | Valid |
| | ERR | Indicates an error *1 | Error | Normal | | Valid | | |
| 0114/0 | NEU | Indicates neutral status *2 | Waiting to receive an MC command | Receiving an MC command | Valid | Invalid (off) | Invalid (off) | Invalid (off) |
| CH1/2 | SD | Indicates send status | Sending data | Not sending data | 17. 11.1 | /alid Valid | Valid | Valid |
| | RD | Indicates receive status | Receiving data | Not receiving data | valid | | | |

^{*1} This indicator turns on when an error occurs in the hardware or data communication of a serial communication module.

On: Waiting to receive a command from the 3rd party device

Off: A command from the 3rd party device is being received or processed.

^{*2} This indicator indicates status of data communication by the MC protocol.



2.2 Communication Cable Connection



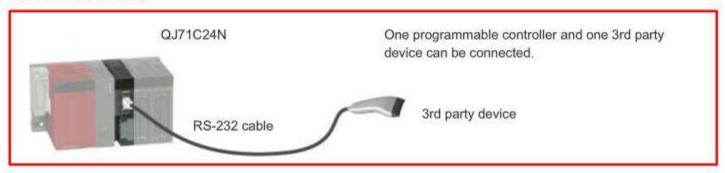
This section shows connection examples with serial communication modules.

2.2.1 Connecting the RS-232 interface to a device

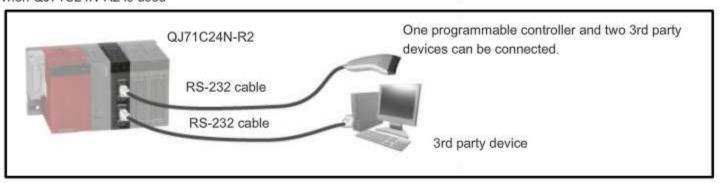
Below are the connection examples for the RS-232 interface, its 3rd party device and the QJ71C24N and QJ71C24N-R2.

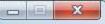
Connection example

When QJ71C24N is used



When QJ71C24N-R2 is used





2.2.2 Wiring for the RS-232 control signals



Click the buttons below to visualize the corresponding wiring examples.

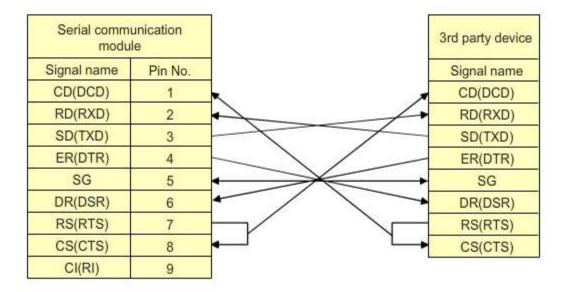
The 3rd party device turns on/off the CD signal.
DTR/DSR control and DC code control are supported.

The 3rd party device does not turn on/off the CD signal.
DTR/DSR control and DC code control are supported.

The 3rd party device does not turn on/off the CD signal.

The 3rd party device does not turn on/off the CD signal.

DC code control is supported.



- · The flow control method of the 3rd party device is employed by the both devices.
- If the 3rd party device has a wiring example for the Mitsubishi serial communication module, follow that example.

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Serial Communication Module Communication Protocols

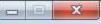
Below are the communication protocols available to a serial communication module.

| Protocol | Details | Control direction |
|---|--|--|
| Non procedure protocol | dure party device. | |
| Predefined protocol Predefined protocol Data communication based on the 3rd party device's protocol is established using the "predefined function". To set a protocol, select a predefined protocol from the communication protocol lib new one, or edit an existing protocol. The selected protocol is written on the flash ROM of the serial communication module and e "dedicated instruction (CPRTCL)". Details of the predefined protocol support function are given in Chapter 3. | | controller to the 3rd party device (Active) |
| MC protocol | MC protocol is the communication method for programmable controllers. With this method, a 3rd party device reads or writes the device data and programs of a CPU module via a serial communication module. If a 3rd party device can send or receive data by the MC protocol, it can access a CPU module. | From the 3rd party device to the |
| Bi- directional protocol | This simple predefined protocol allows external devices such as personal computers, to send and receive data comparatively easily. A programmable controller uses dedicated instructions (BIDIN, BIDOUT) to respond to the external device. | programmable controller (Passive) |

Active: A programmable controller gives instructions to its 3rd party device and receives a response.

Passive: A programmable controller receives instructions from the 3rd party device and returns the value and status saved in its devices as responses.

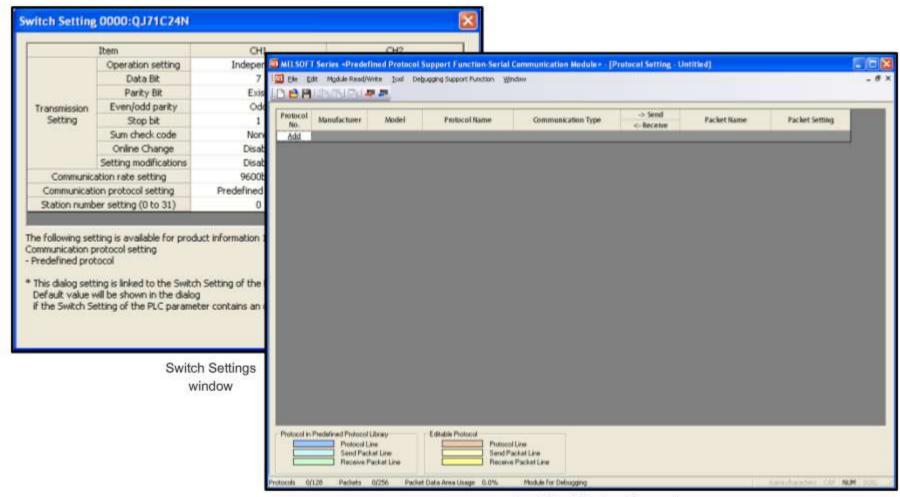
The example system in this course uses "predefined protocol".



Serial Communication Module Configuration



GX Works2 is useful in configuring initial settings and registering predefined protocols (predefined protocol support function) to the serial communication modules. Please refer to Chapter 3 for details.



Predefined Protocol Support Function window





Summary

In this chapter, you have learned:

- · Serial communication modules types
- · Communication cable connection
- · Serial communication module communication protocols
- · Serial communication module configuration

Important points

| Data communication protocols | The data communication protocols available to a serial communication module are: non procedure protocol, bi-directional protocol, MC protocol, and predefined protocol. |
|------------------------------|---|
| Predefined protocol | The "predefined protocol support function" creates a predefined protocol based on the 3rd party device's protocol |
| Connection method | QJ71C24N can be connected to a 3rd party device via an RS-232 or RS422/485 interface. QJ71C24N-R2 can be connected to two 3rd party devices via an RS-232 interface. |

Chapter 3 Initial Configuration

Chapter 3 describes how to setup a serial communication module for its initial operation. This chapter especially focuses on the programing method that uses dedicated instructions.

All the knowledge required to operate a serial communication module (system configuration, connection method, and various settings and operations of a serial communication module) are covered in this chapter.

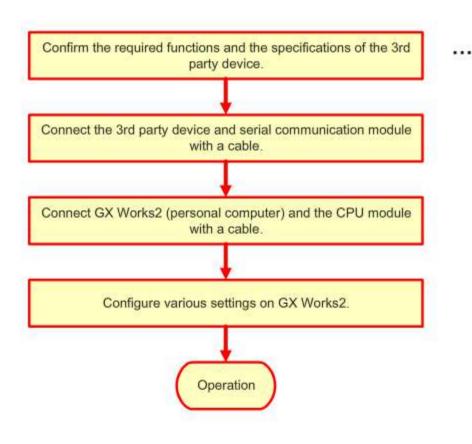
- 3.1 Settings Before Operation and Setting Procedure
- 3.2 Parameter Settings
- 3.3 Parameter Writing
- 3.4 Predefined Protocol Support Function
- 3.5 Dedicated Instructions
- 3.6 Summary

Settings Before Operation and Setting Procedure



This section describes the system structure containing a connected 3rd party device, as well as the serial communication module settings and cable connection methods.

The set-up procedure for a serial communication module is shown below.



| Specifications of the used in the ex | ne bar code reader ample system |
|--------------------------------------|------------------------------------|
| Interface | RS-232 |
| Baud rate | 9600 bps |
| Data bit | 7 bits |
| Parity bit | Present |
| Parity | Odd number |
| Stop bit | 1 bit |
| Receive complete code | CR+LF |

3.1.1 Example system structure





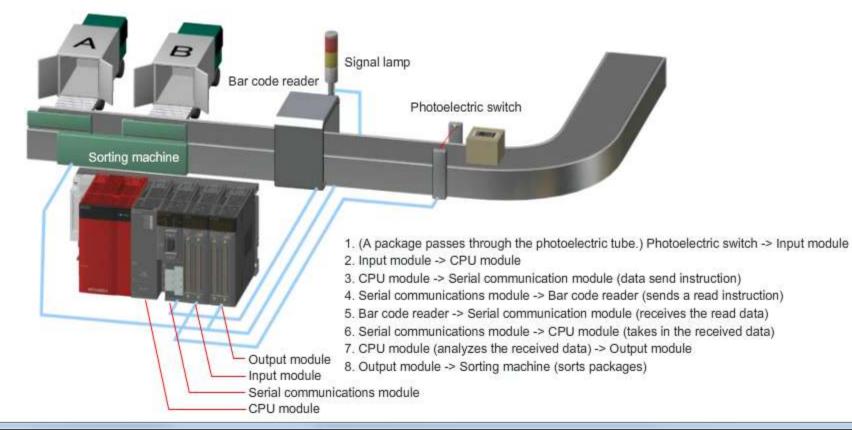


Structure

- A bar code reader and a signal lamp are installed close to each other.
- The bar code reader is connected with programmable controllers including a serial communication module via an RS-232 interface.

Operation

- A package moving on a conveyor is detected.
- After the detection, the bar code reader reads the bar code on the package.
- The read data is sent as a variable-length data with a receive complete code [CR+LF] appended, to the serial communication module.
- The read data is then saved in the CPU module devices.



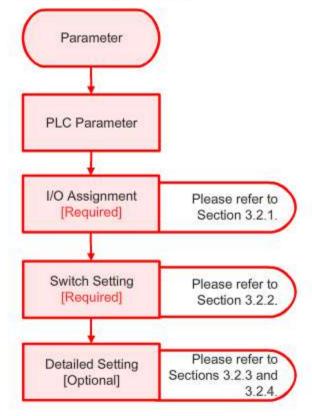
Parameter Settings



Various settings need to be configured through GX Works2 to establish data communication with a 3rd party device.

Parameter setting overview

- The model, installation slot No., start I/O number, etc. of the serial communication module are set in "I/O Assignment".
- The transmission speed, communication speed, etc. of the serial communication module are set for each channel in "Switch Setting".
- The control method is set in "Detailed Setting" in accordance with the control target of the serial communication module.

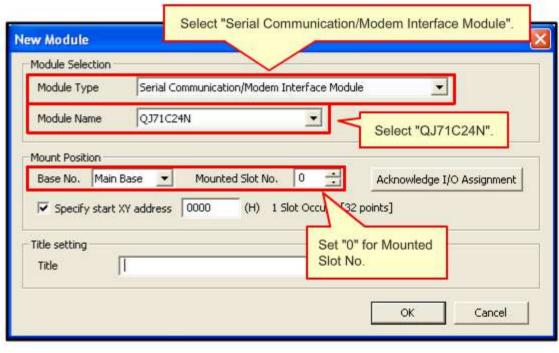


3.2.1 I/O assignment setting



The model, installation slot No., start I/O number, etc. of the serial communication module to be installed on the base unit are configured in "New Module" window.

To add a new module in GX Works2, select "PLC Parameter" - "I/O Assignment" - "New Module".

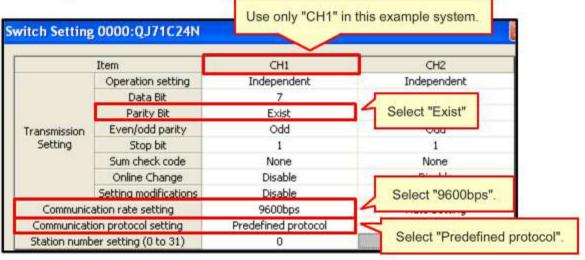


New Module window

3.2.2 Switch settings

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The transmission speed, communication speed, etc. of a serial communication module are set for each channel in "Switch Setting". In GX Works2, select "Intelligent Function Module" - "0000: QJ71C24N" - "Switch Setting".



Switch Setting window

| | Item | Item setting details | |
|----------------------------------|-----------------------|--|--|
| | Operation setting | Set whether two channels are used separately or linked for data communication. | |
| | Data bit | Set the bit length of one character in the communication data. | |
| | Parity bit | Set whether to add a parity bit to the communication data. | |
| Transmission | Even/odd parity | Set whether to add an odd or even parity bit. | |
| Setting | Stop bit | Set the stop bit length of the data exchanged with the 3rd party device. | |
| | Sum check code | Set whether to add a sum check code to sent and received messages. | |
| 1 | Online change | Set whether to write while the CPU module is in the "RUN" state. | |
| | Setting modifications | Set whether to permit changes to the settings after the module has started up. | |
| Communication rate setting | | Set the speed of communication with the 3rd party device. | |
| Communication protocol setting | | Set the details of communication with the 3rd party device. | |
| Station number setting (0 to 31) | | Set the station number set by the 3rd party device when MC protocol is used. | |
| | | | |



3.2.3 Changing the word/byte unit

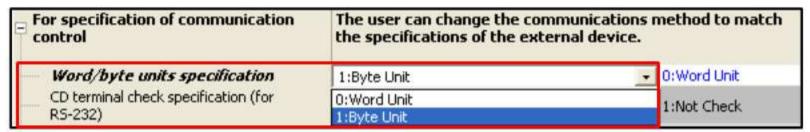




Set the unit of sent/received data to word or byte.

The default unit is word. This setting needs to be changed in order to handle data in byte units.

In GX Works2, select "Intelligent Function Module" - "Various Controls Specification".



Various Control Specification window

3.2.4

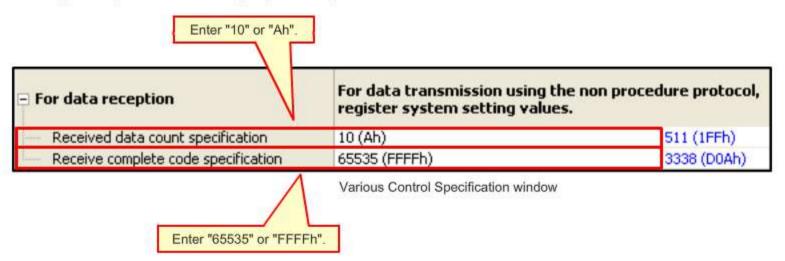
Changing the receive data count and receive complete code



The received data (size) count and the data receive complete code can be configured. In GX Works2, select "Intelligent Function Module" - "Various Controls Specification".

| Reception method | Received data count Default value: 511 (1FFH) words | Receive complete code Default value: CR+LF |
|--------------------|---|---|
| Variable length | To receive data equal to or smaller than the default value, use this setting as it is. To receive data exceeding the default value, change this setting together with other settings. For details, please refer to the corresponding manual of the serial communication module. | To use a receive complete code other than the default value, change this setting. |
| Fixed length | Change the setting according to the length of the received data. | Change to "Not specified (FFFFH)". |

Setting example for a fixed-length (10 words) data

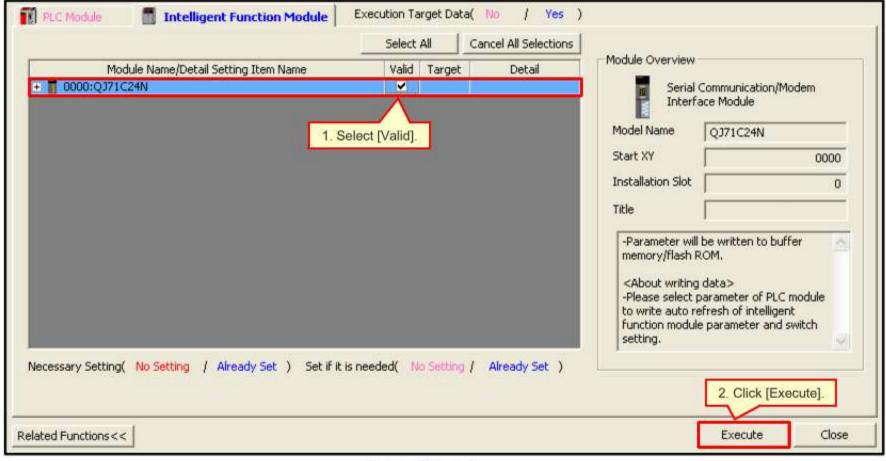




3.3 Parameter Writing



The switch settings and various control specifications that have been configured in GX Works2 need to be written to the serial communication module. In GX Works2, select "Online" – "Write to PLC" - "Intelligent Function Module" tab.



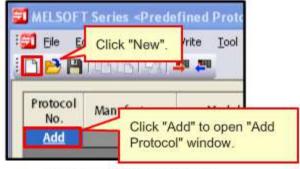
Write to PLC window

Predefined Protocol Support Function



The "predefined protocol support function" of GX Works2 enables protocol communication with a 3rd party device by using simple sequence programs containing dedicated instructions. The predefined protocol support function reduces the program size and program-creation time as compared to using individual sequence programs.

In GX Works2, select "Tool" – "Predefined Protocol Support Function" - "Serial Communication Module" to open the "Predefined Protocol Support Function" window.



Predefined Protocol Support Function window

Some predefined protocols are already in GX Works2, but if the protocol of the 3rd party device is not found, new protocol can be created.

(1) When the predefined protocol is already in GX Works2

Select the manufacturer, model, and protocol name in the "Add Protocol" window.

(2) When the predefined protocol is not found in GX Works2

Create a new predefined protocol.

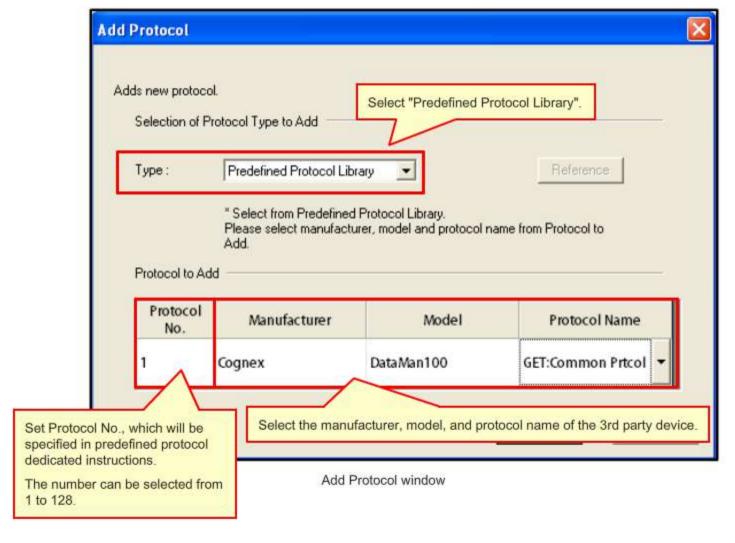
In the example system of this course, the predefined protocol will be newly created according to the 3rd party device.

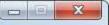
3.4.1 Adding a protocol

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(1) When the predefined protocol is already in GX Works2

When the desired predefined protocol already exists, select the manufacturer and model in the "Add Protocol" window to register it.



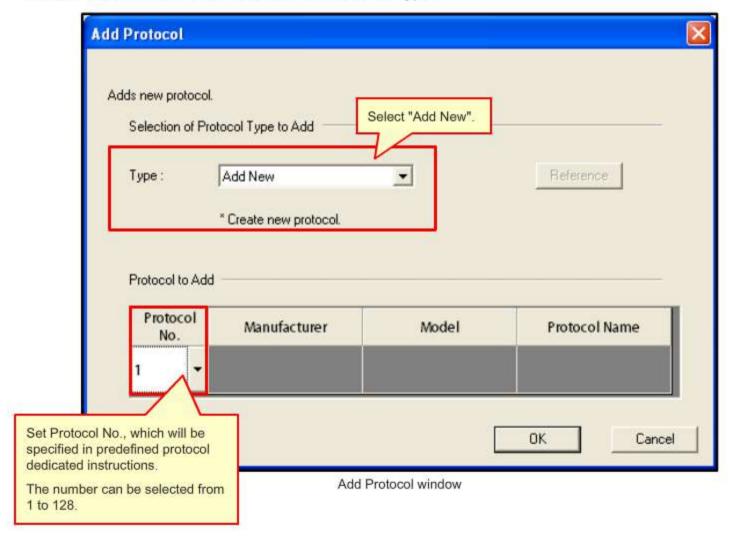


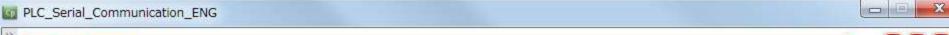
3.4.1 Adding a protocol



(2) When the predefined protocol is not found in GX Works2

On the "Add Protocol" window, select "Add New" at Type.

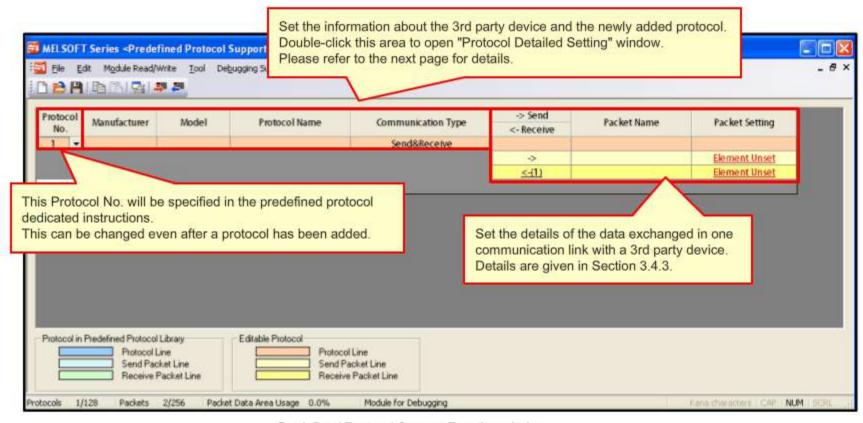




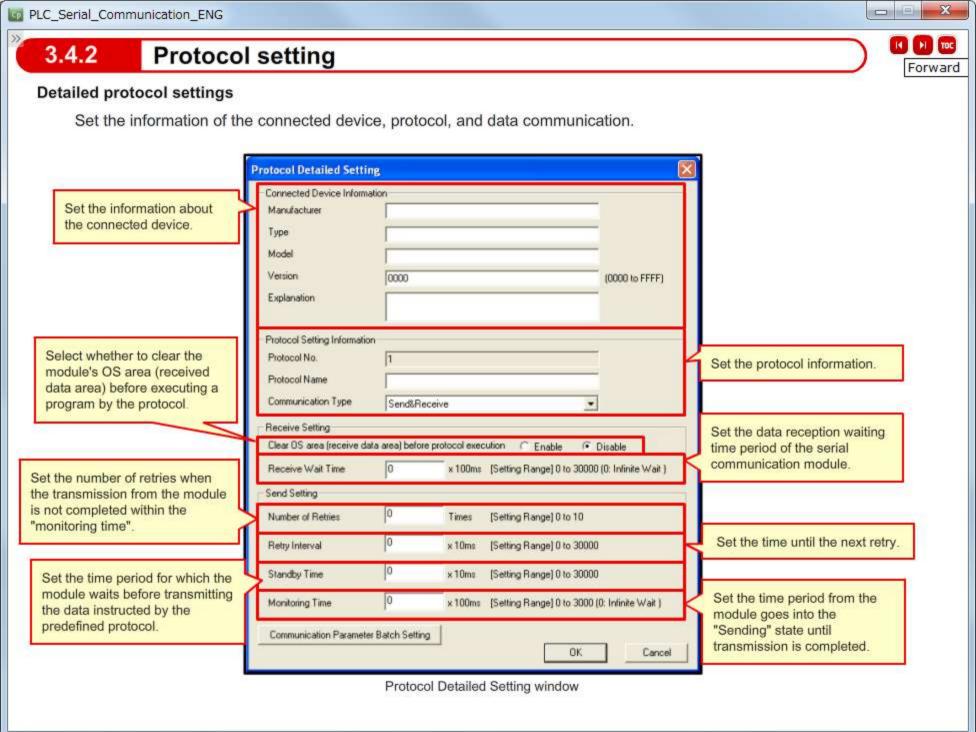
3.4.2 Protocol setting

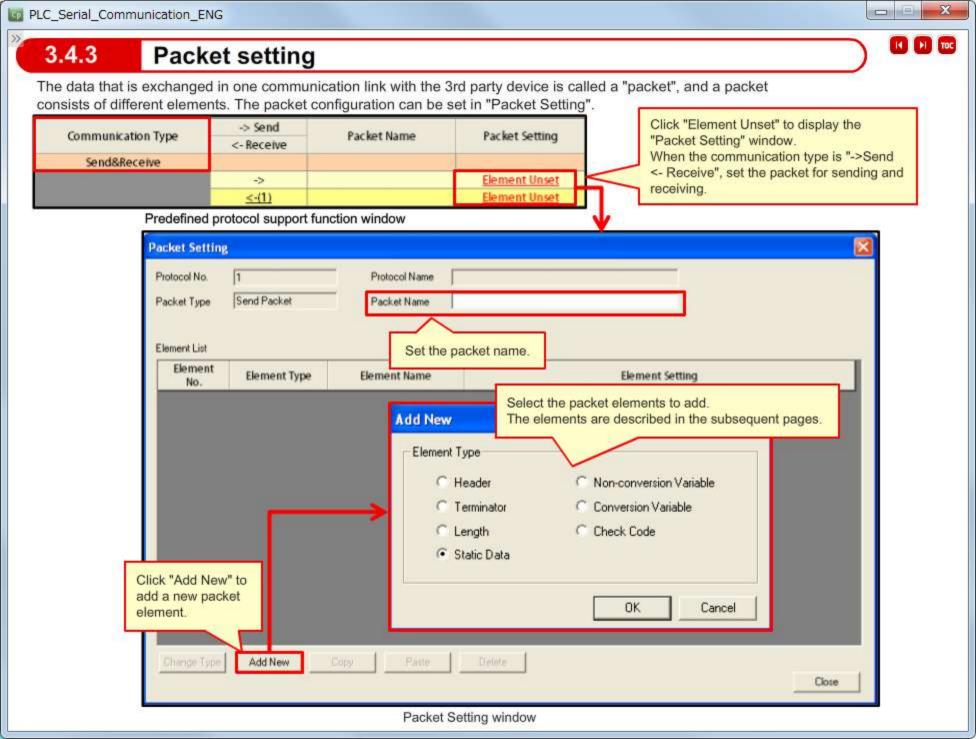


Set the information of the newly added predefined protocol and the details of the communication data.



Predefined Protocol Support Function window









Header

A specific code or character string can be added to the head of a packet.

- · When transmitted: The specified code or character string is sent.
- · When received: The header is verified against the received data.

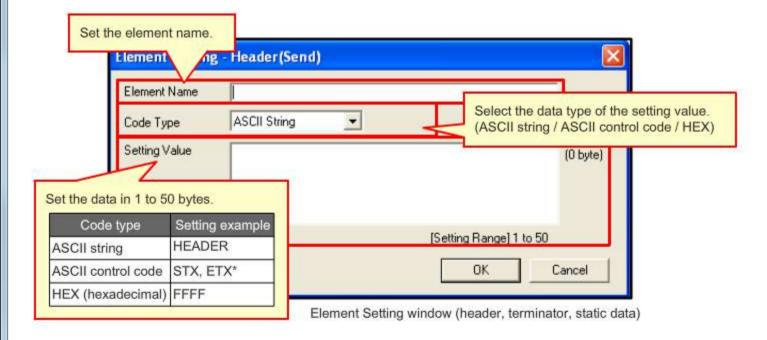
Terminator

A code or character string can be added to indicate the end of a packet.

Static data

A specific code or character string, such as a command, can be included in a packet.

- · When transmitted: The specified code or character string is sent.
- · When received: Received data is verified.

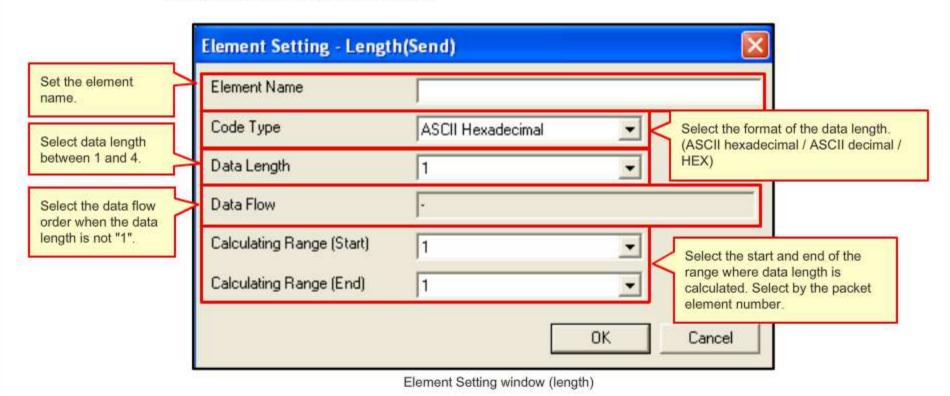


^{*} STX: Start of text, ETX: End of text

Length

An element indicating the data length can be included in a packet.

- When transmitted: Data length of the specified range is automatically calculated, added to the packet, and sent.
- When received: The received data is checked against the data length information (value) contained in the received data.

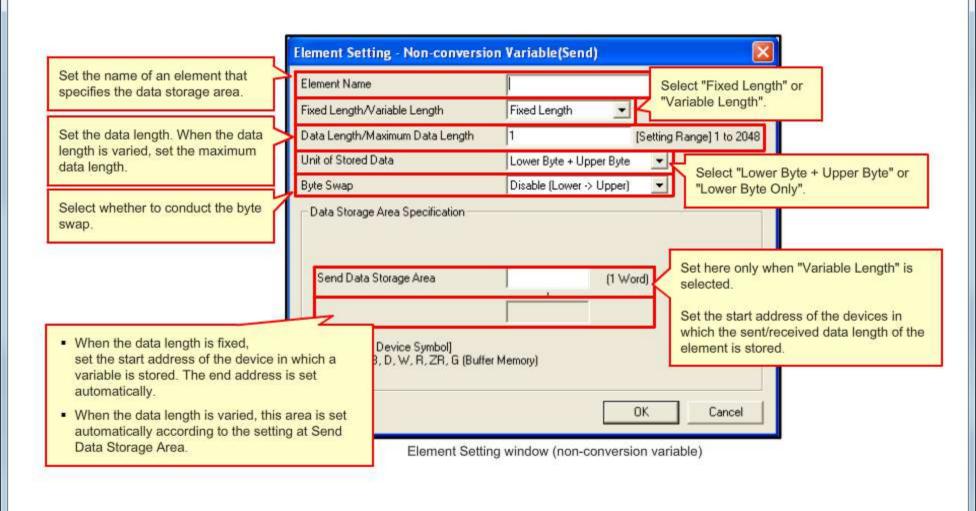


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Non-conversion variable

Use a non-conversion variable when:

- · Data in a device or the buffer memory is sent as it is without data conversion.
- · Part of a received packet is stored in a device or buffer memory without data conversion.

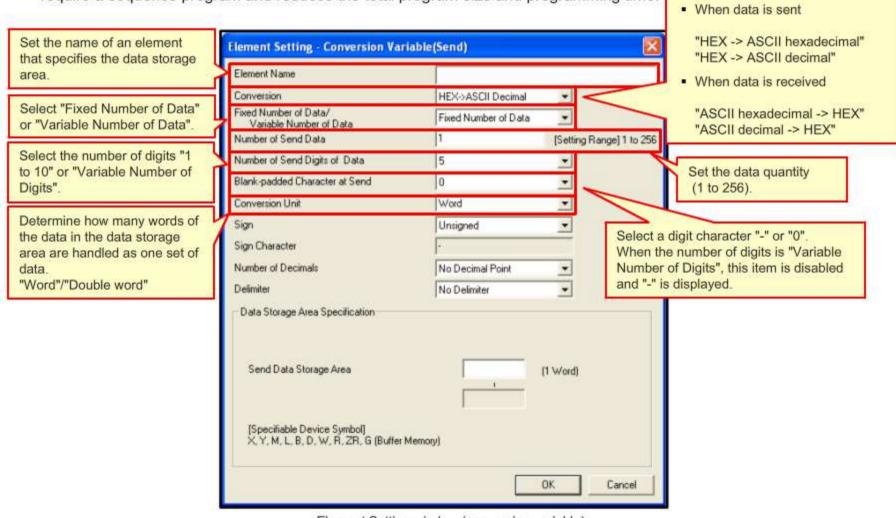






Conversion variable

The data in the device or buffer memory is sent after being converted, and received data is converted and then stored in the device or buffer memory. This data conversion process does not require a sequence program and reduces the total program size and programming time.



Element Setting window (conversion variable)

(Continued on the next page)

* Select "+". Negative values always need the "-" symbol.

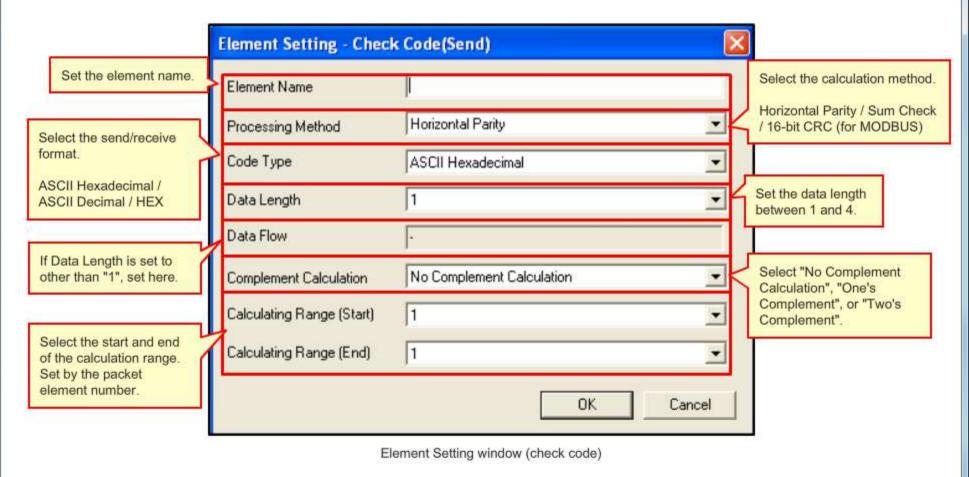
X

3.4.4 Packet element type

Check code

An element that checks for incorrect data can be included in a packet.

The check code can be added to a transmitting packet or used against a reception packet. The check code calculation is automatically performed at data reception/transmission.



3.4.5 Setting of the example system

This section explains the packets sent/received by the predefined protocol in the example system.

(1) Send packet

The send packet contains the command character string for instructing a bar code read. It is composed of the header character string "M", command character string "TR" (static data, ASCII character) and packet end code "CR+LF" (terminator, ASCII character).

| Protocol No. | 1 | Protocol Name | Bar code reader | | |
|--------------------|------------------------------------|---|-----------------|--|--|
| Packet Type | Send Packet | Packet Name | BR read trigger | | |
| Element List | | | | | |
| Element | Flament Type | Floment Name | Flament Setting | | |
| A Charles of Sales | Element Type | Element Name | Element Setting | | |
| Element | Element Type Header | Element Name Header | Element Setting | | |
| Element | Note that the second second second | 100000000000000000000000000000000000000 | | | |

Packet Setting window (send packet)

(2) Receive packet

The receive packet contains the country ID code (JPN/USA) that has been read by the bar code reader. The receive packet is composed of the number of country ID code characters "3" (static data, ASCII character), the country ID code (non-conversion variable, ASCII character), and a packet end code "CR+LF" (terminator, ASCII character). After the packet is received, the country ID code is stored in the devices "D600" and "D601".

| Protocol No. | [1 | Protocol Name | Bar code reader |
|----------------|----------------------------|---------------|--|
| Packet Type | Receive Packet | Packet Name | BR read data output |
| Packet No. | 1 | _ | |
| Element List | 77 | | |
| Element No. | Element Type | Element Name | Element Setting |
| 1 | Header | Header | "M "(2Byte) |
| 2 | Static Data | # of chara. | "3"(1Byte) |
| 3 | Non-conversion Variable | Read data | [D600-D601](Fixed Length/3Byte/Lower/Upper Byte/No Swap) |
| 4 | Terminator | Footer | "CRLF"(4Byte) |

Packet Setting window (receive packet)

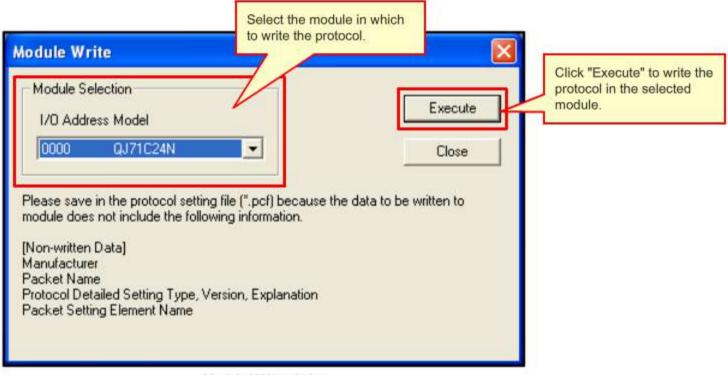
3.4.6 Saving and writing created protocols



To save the created protocol in a protocol setting file, select "File" - "Save as" in the Predefined Protocol Support Function window.

The created protocol needs to be written in the serial communication module.

Select "Online" - "Module Write" in the Predefined Protocol Support Function window.



Module Write window

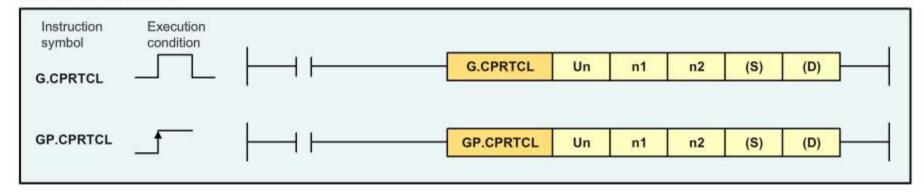


3.5 Dedicated Instructions



Dedicated instructions of sequence programs can be used to execute the predefined protocol, which has been written in the module.

Dedicated instruction



Setting data

| Setting data | Details | Setting by | Data type | Value for the example system Set the module installation slot 0. | |
|--------------|---|--------------|----------------------------|---|--|
| Un | Start I/O signal of the module (00 to FE: First two digits of the three-digit I/O signal) | User | BIN 16 bits | | |
| n1 | Channel for communicating with a 3rd party device 1: Channel 1 (CH1 side) 2: Channel 2 (CH2 side) | User | BIN 16 bits device name | Set "1" to use Channel 1 | |
| n2 | Continuous protocol execution count (1 to 8) | User | BIN 16 bits device name | Number of protocols processed at a time. Set "1". | |
| (S) | Start number of the device in which control data is stored. | User, system | Device name | Set "D500". | |
| (D) | Device number of the bit device to be turned on when execution is completed. | System | Bit | "M1000" | |



3.5

Dedicated Instructions



Control data

Control data is the data area storing the parameters to be executed by the GP.CPRTCL instruction. The execution results are also saved here.

| Setting data | Item | Set data | Setting range | Set by | Value for the example system | |
|-------------------|--|---|---------------|--------|--|--|
| (S) + 0 = D500 | Execution result | Execution result of the G (P).CPRTCL instruction. When multiple predefined protocols are executed, the execution result of the last executed predefined protocol is stored. 0: Normal Value other than 0: Error code | | System | "0" denotes normal response. When error, an error code is written automatically by the system. | |
| (S) + 1 = D501 | Receive result | Number of executed predefined protocols. A protocol that has caused an error is also included in the number of executed protocols. "0" is stored when there is an error in the setting data or control data settings. | 1 to 8 | System | A normal response, "1", is written automatically by the system. | |
| (S) + 2 = D502 | The protocol No. to be executed first, or the protocol No. of a functional protocol. | | 1 to 128 | User | Write "1" in | |
| - | to be | Name | | | D503 because only the protocol | |
| (S) + 9 = D509 | executed | The protocol number to be executed at the 8th order, or the protocol No. of a functional protocol. | 201 to 207 | | No.1 is used. | |

3.6





Summary

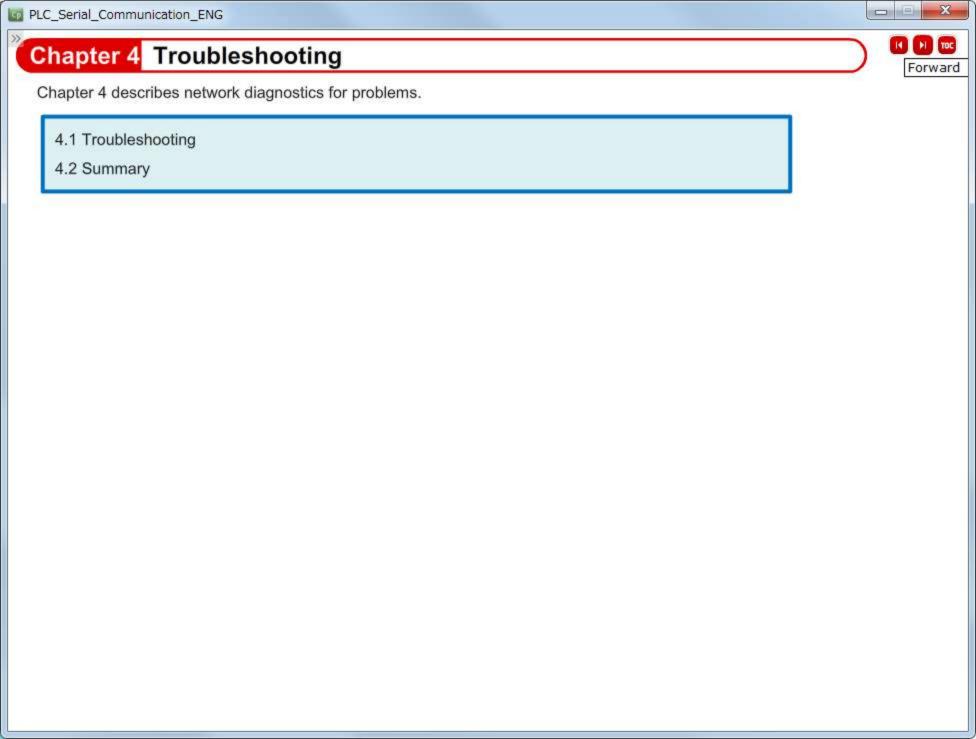
In this chapter, you have learned:

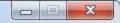
- · Settings before operation and setting procedure
- · Setting parameters using GX Works2

- · Predefined protocol support function
- · Dedicated instructions
- · Sequence program example

Important points

| Setting parameters using GX Works2 | The switch settings and various control settings are configured using GX Works2. GX Works2 also configures the necessary settings to a serial communication module that will be installed on a programmable controller. |
|--------------------------------------|--|
| Parameter writing | The switch setting and various control settings that have been configured by GX Works2 need to be written in a serial communication module. |
| Predefined protocol support function | The "predefined protocol support function" of GX Works2 enables data communication with a 3rd party device in accordance with the 3rd party device's protocol. The function uses simple sequence programs containing dedicated instructions. |
| Dedicated instructions | The predefined protocol written in the flash ROM can be executed using the dedicated instructions (CPRTCL). |





4.1 Troubleshooting



Below are the details of the errors that can occur in data communication between a serial communication module and a 3rd party device, and corrective actions for the errors.

| Problem | Possible cause | Corrective action | Reference |
|--|---|---|------------------|
| ERR LED turns on. | A communication error has occurred. | Check the error code on the system monitor and remove the cause of the error. | Section 4.1.1 |
| "RD" does not flash when the 3rd party device sends a message. | The send control signal of the 3rd party device is off. | Adjust the wiring so that the CTS signal on the 3rd party device is ready. | 122 |
| "SD" does not flash when a send request is transmitted from the serial communication module. | The RS-232 control signals, "DSR" or "CTS", are off. "DSR" or "CTS", are off. | Check the status of each RS-232 control signal. | Section 4.1.2 |
| Although "RD" flash after the 3rd party device sends a message, the receive and read | The predefined protocol setting is incorrect. | Check the predefined protocol setting. | Section 3.2.2 |
| request signal (X3/XA) of the serial communication module does not turn on. | The 3rd party device did not add the receive complete code. | Check the sent/received data using the circuit trace function. | Section 4.1.3 |



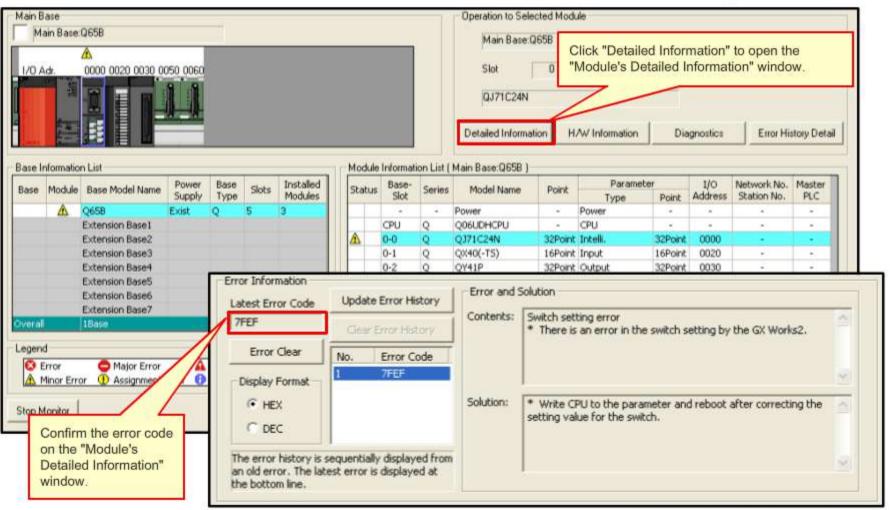
4.1.1 Checking the error codes on the system monitor

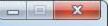


Error codes can be confirmed on the system monitor.

In GX Works2, select "Diagnostics" - "System Monitor".

System Monitor window



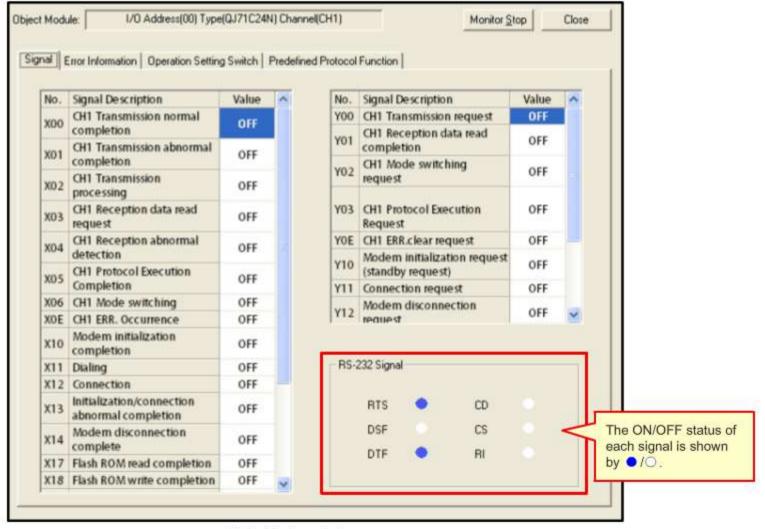


4.1.2 Checking the signals on the state monitor



On the State Monitor window, a user can check the RS-232 control signal statuses. The status of each signal to/from the serial communication module can also be checked.

In GX Works2, select "Predefined Protocol Support Function" - "Debugging Support Function" - "State Monitor".



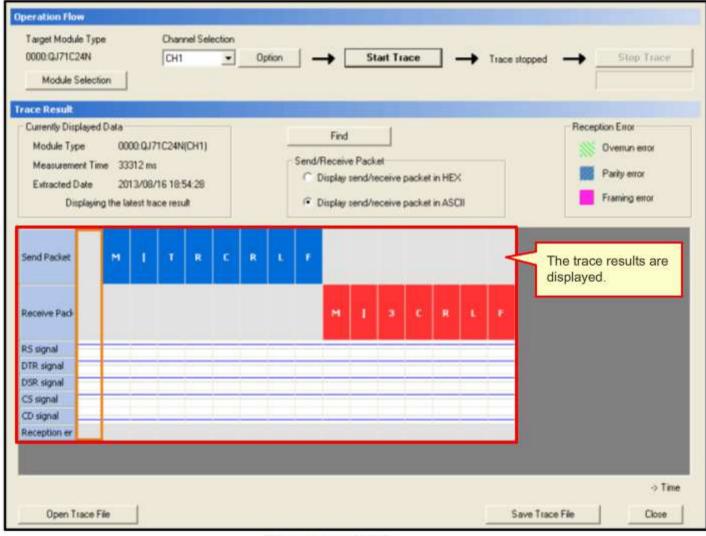


4.1.3 Checking the sent/received data using the circuit trace



Check the sent/received data using the circuit trace function.

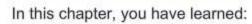
In GX Works2, select "Tool" - "Intelligent Function Module Tool" - "Serial Communication Module" - "Circuit Trace".



4.2







Troubleshooting

Important points

| Checking the errors when ERR. LED is on | An error is indicated by the ERR. LED indicator on the serial communication module. |
|--|---|
| Checking the RS-232 control signal errors | The status of each signal can be checked on the state monitor. |
| Checking the errors using the circuit trace function | Using the circuit trace function, errors in sent/received data can be checked. |







Now that you have completed all of the lessons of the PLC Serial Communication Course, you are ready to take the final test. If you are unclear on any of the topics covered, please take this opportunity to review those topics.

There are a total of 11 questions (30 items) in this Final Test.

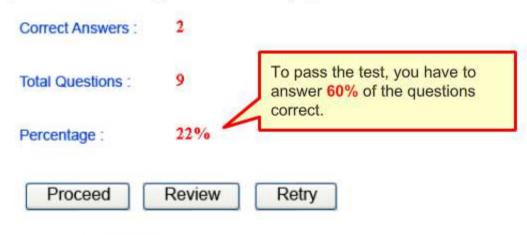
You can take the final test as many times as you like.

How to score the test

After selecting the answer, make sure to click the **Answer** button. Your answer will be lost if you proceed without clicking the Answer button. (Regarded as unanswered question.)

Score results

The number of correct answers, the number of questions, the percentage of correct answers, and the pass/fail result will appear on the score page.



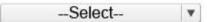
- Click the Proceed button to exit the test.
- Click the Review button to review the test. (Correct answer check)
- Click the Retry button to retake the test again.



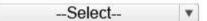
Flow control

Please select the correct term for each description.

(1) A control method that adjusts data send timing using a flow control line installed separately from the signal line, in the same cable. :



(2) A control method that adjusts data send timing using specific codes. :



Answer

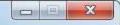


RS-232 cable

Please select the correct description about the RS-232 cable used for a serial communication module.

- Any RS-232 cross cable available on the market can be used.
- A cable must be carefully selected in accordance with the protocol of the 3rd party device.

Answer



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Data reception procedure

The table below lists data reception methods available to a serial communication module. Please select the correct data reception procedure for each description.

| Characteristics of the data received from the 3rd party device | Data reception procedure |
|---|--------------------------|
| The data length is varied. The data has CR+LF added at the end. | –Select– ▼ |
| The data length is fixed to 4 bytes. | Select ▼ |
| The data length is varied. The data has no receive complete code. | —Select— ▼ |

Answer

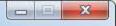
Final Test 5 Test



Data exchange procedure

The table below lists protocols available to a serial communication module. Please select the correct protocol for each description.

| Protocol | Description |
|-------------|--|
| Select ▼ | Data can be exchanged between the 3rd party device and a CPU module in any message format and by any communication protocol. |
| Select ▼ | Communication protocol for the Q series programmable controllers. By this protocol, the 3rd party device reads or writes the device data and programs of a CPU module via a serial communication module. |
| Select ▼ | This protocol is used when data communication needs to be established according to the protocol of the 3rd party device, such as a measuring instrument or a bar code reader. |
| -Select- ▼ | If the 3rd party device can send or receive data by MC protocol, it can access a CPU module. |
| Select ▼ | By using an existing simple protocol, data can be exchanged relatively easily with an external device such as a personal computer. |
| Select ▼ | Data communication by the 3rd party device's protocol is realized using the "predefined protocol function". |
| Answer Back | <u> </u> |



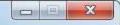


Non procedure protocol

The following descriptions are about data communication by non procedure protocol. Please select the correct terms to complete the sentences.

| Description | | | | | | |
|-------------------------|--------------------------|-------|-------------|-----------------------|-------------|---|
| To receive code is used | Select- d. To receive | | data in a [| Select data, a rec | ▼] eived | by non procedure protocol, a receive complete data count is used. |
| The receive | complete code | and I | received da | ita count can b | e set | toSelect▼ to receive data. |

Answer





GX Works2

The table below explains the received data count and receive complete code settings in GX Works2. Please select the correct values and terms to complete the table.

| Data reception procedure | Received data count Default value: (Select ▼) words | Receive complete code Default value: (Select-) |
|--------------------------|--|---|
| Fixed length | If the received data count is lower than the default value, the setting change is Select If the received data count is higher than the default value, the setting change is Select Select Select Select Select Select | If the receive complete code is different from the default value, the setting change isSelect ▼ . |
| Variable length | The setting change is required in accordance with the received data length. | The setting must be changed to "Not specified (FFFFH)". |

Answer



Operation check 1

Please select the sentence that correctly describes the RS-232 control signals, which are used between a serial communication module and its 3rd party device.

- The signal status can be checked from the "System Monitor" of GX Works2.
- The signal status can be checked from the "State Monitor" of GX Works2.
- The signal status can be checked from the "Circuit Trace" of GX Works2.

Answer

Final Test 9 Test



Operation check 2

The table below shows troubleshooting for data communication failure between a serial communication module and its 3rd party device.

Please select the correct item for each of the possible cause and corrective action.

| Symptom | An external device transmitted a message and "RD" blinked, but the read request signal (X3/XA) from the serial communication module was not turned on. |
|-------------------|--|
| | Q1 (A) A communication error is occurring. |
| Possible | (B) The transmission control signal is off at the 3rd party device. |
| cause | (C) Communication protocol is set incorrectly. |
| | The receive complete code was not added by the 3rd party device. |
| | Q2 (D) Check the error code in the system monitor, and remove the error cause. |
| Corrective action | (E) Check if the CS signal is on using the state monitor. |
| | (F) Check the communication protocol setting. |
| | Check the send/receive data with the circuit trace function. |

Q1 🔻 Q2 v Back Answer

Final Test 10 Test





Predefined protocol support function 1

Please select the sentence that correctly describes the predefined protocol support function.

- This function enables protocol communication with a 3rd party device by using simple sequence programs containing dedicated instructions.
- This function enables automatic analysis of communication parameters transmitted from the 3rd party device so that a protocol suitable for the 3rd party device can be created.

Answer



Predefined protocol support function 2

The sentences below respectively describe "non-conversion variable" and "conversion variable". Please select the correct term for each description.

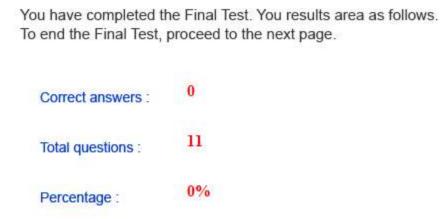
(1) Data are sent and received without being converted. ::



(2) Data are sent and received after being converted.

This data conversion process does not require a sequence program and reduces the total program size and programming time. : --Select--

Answer



Review

Test Score

PLC_Serial_Communication_ENG

Proceed

Test

You failed the test.

Retry

×

